











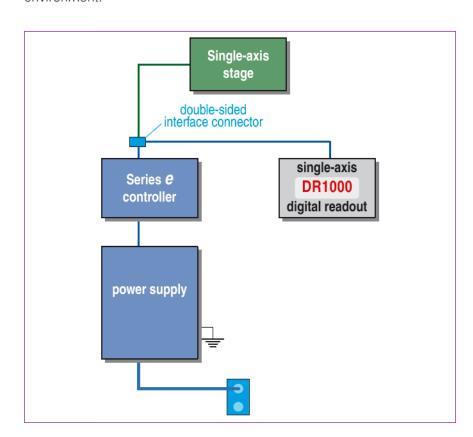
# Siskiyou Motion Control Products

Siskiyou translation stages are designed with multiple applications in mind. Siskiyou's motion controllers provide intuitive and accurate control over a full range of actuators, manipulators, and stages. The Siskiyou family of controllers includes single-axis up to 4-axis devices. They utilize a CE certified power supply as a source for clean DC power for the operation of DC servo motors. All cables are shielded, and a central ground is provided to ensure noise-free operation during sensitive electrophysiology experiments. In addition, they are frequently used in controlling microscope, headstage, probe, optics, and fiber optics positioners. Hydraulic controllers for one- or 3-axis control are found in the Life Science section.

All of our controllers come complete with the power supply and power cables needed to operate our motorized equipment. Because each installation is different, grounding cables are not included and must be supplied by the end user.

The MC1000e series of motion controllers uses a closed loop signal between the controller and the motor encoder for smooth, responsive motion. The MC2010 motion controller also uses a closed loop signal between the controller and the motor encoder, but is operated by a usersupplied personal computer. LabVIEW™ is the flexible operating platform used to drive the MC2010. LabVIEW™ is a trade name for National Instruments software, the industry standard in the laboratory automation environment.

# **Typical Installation Schematic**



www.siskiyou.com

Many of our products utilize symbols or color coding where appropriate. For example, on our motion controllers, a rabbit icon  $\ \ \ \ \$  is used to show fast, rapid, or high speed settings. This setting is typically used for coarse positioning, where positioning accuracy of 15  $\mu m$  or greater is adequate.

For slow speed or high resolution settings, a turtle icon  $\varnothing$  is used. This setting is typically used for positioning accuracy of 2  $\mu$ m or less. On manually adjusted stages or manipulators, color coded SoftTouch<sup>TM</sup> knob caps are used to identify axis adjustment at a glance, especially in low light conditions.

The DR1000 is an example of our Modular by Design™ philosophy. This standalone digital readout is compatible with all of our MC1000e series controllers. The DR1000 is a cost-effective alternative to a PC operated controller — you don't need an active computer to display position. A DR1000 is shown in the typical installation schematic on page 20.

For sensitive electrophysiology experiments it is critical to ground electrical connections. All our controllers come with grounding lugs on the junction box. It is important to read the instruction manual completely before attempting to use any controller or related equipment.

Every effort has been made to protect the equipment and the user from accidental shock. If a saline solution used in electrophysiology experiments is spilled on the control pendant of a series controller, it is possible that the circuitry would be damaged but highly unlikely that the user would be shocked. As with any accident, unplug the equipment. See Ordering Information for instructions on returning the unit to Siskiyou for repair.

Siskiyou controllers are compatible with other comparable DC servo devices. Please contact us for compatibility specifications.

# **Motion Control**

## **Closed Loop Controllers**

Push Button Control	
1 Axis, Push Button	22
4 Axis, Push Button	23
Micrometer Dial Control	
1–4 Axis, Single Micrometer Dial	24
4 Axis, Micrometer Dial	25
Joystick Control	
3 Axis, Joystick	26
Computer Interface Control	
4 Axis, Computer Interface	27

#### **Open Loop Controllers**

Push Button Control	
1 & 4 Axis, Push Button	28
1 & 4 Axis, Push Button Microdrive	29

#### Accessories

1-4 Axis, Switch / Junction Box	30
1 Axis, Digital Readout / Display	31
25 Pin Sub-D Polarity Adapter	3.

Siskiyou controllers are compatible with other comparable DC servo devices. Please contact us for compatibility specifications.



# Closed Loop Controllers

**Motion Control** 

**CE** Certified

# 1 Axis Push-Button Control / MC1000e-1

MC1000e-1. MC1000e and MC1100e pendant dimensions are identic



1.95 25 Pin D Female connector for motorized O Sign drive interface 72-inch cable Power 5.85 3.70

MC1000e-1

# **Product Features**

- Economical DC controller
- Variable, high resolution speed control
- Preset rapid and medium speed setting
- User set TARGET point (MC1100e)

# Performance Specifications

Minimum controllable motion	0.2 μm
Power requirements	110-230 VAC, 50/60 Hz

#### **Related Products**

MX1641 micromanipulators	167
800 and 7000 series translation stages	63
800 and 7000 series actuators	93
100cri stages	64
200cri stages	64
DR1000 digital readout	31

#### **Order Information**

1-axis, closed loop controller	MC1000e-1
4-axis, closed loop controller	MC1000e
4-axis, closed loop controller w/ TARGET	MC1100e

## 1 and 4 Axis Push Button Controllers

The MC1000e and MC1100e are simple push-button controllers with submicron positioning capability, and compatible with our 800 and 7000 series actuators, manipulators, and stages. These controllers have two preset speed settings: rapid (1.7 mm/second) and medium (300 µm/second). The third speed selector (slow) has a variable 330° potentiometer that enables settings from high speed (50 µm second) to low speed (2 µm/second). With the speed selector set at the slowest settings, consistent 0.2 µm moves are easily made by the simple bump of an axis button. The controller uses encoder feedback from the motor to drive the device. This encoder coupling enables the use of the DR1000 digital readout for repeated positioning requirements. MC1000e and MC1100e use a CE certified power supply as their source for clean DC power.

The MC1100e has a target/retract feature on one axis. Target/retract allows a user to set a target location at a desired point. When it becomes necessary to back away from the experiment area, the user simply presses the RETRACT button on the controller. The stage/actuator plugged into that axis then automatically retracts to its full negative limit. The user can then return to the previously set position by simply depressing the TARGET button.

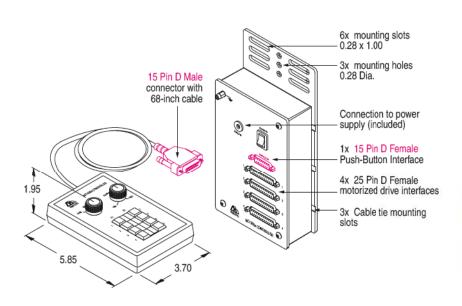
All controller cables are shielded and fitted with a central ground lug located on the junction box to ensure noise-free operation during sensitive electrophysiology experiments.

# **Closed Loop Controllers**

**CE Certified** 

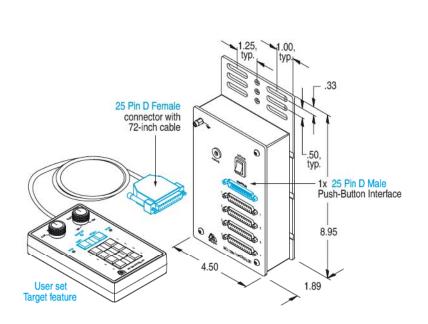
# 4 Axis Push-Button Control / MC1000e

MC1000e and MC1100e component dimensions are identical / Differences are highlighted in ■





## 4 Axis Push-Button Control with Target Functionality / MC1100e MC1000e and MC1100e component dimensions are identical / Differences are highlighted in ■









24

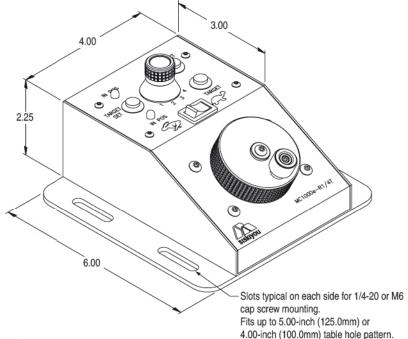




# **Closed Loop Controllers**

**CE** Certified





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Includes a 60-inch controller connection cable

Reverse polarity switch, 4 places

25 pin D sub connector

5.97

# 1–4 Axis Micrometer Dial Control, with Target and Retract Feature

The MC1000e-R1/4T 4-axis dial controller acts as a remote micrometer control with a user selected target feature for 800 and 7000 series actuators, manipulators, and stages. The MC1000e-R1/4T uses encoder feedback from our closed

loop devices to create an electronic link between the controller dial and the device being driven. This direct coupling to the encoder ensures smooth and coordinated motion between the controller and the drive. The encoder coupling enables the use of the DR1000 digital readout for repeated positioning requirements.

A four position rotary switch, mounted on top of the controller, is used to select the desired axis to control. A two-position rocker switch is conveniently located on the top of the controller to allow for rapid and slow travel speed. The rapid  $\mbox{\ensuremath{\ensuremath{\varnothing}}}$  setting is set to maximize speed (1.5 mm/ second) when the dial is turned at 240 RPM. The slow  $\mbox{\ensuremath{\ensuremath{\varnothing}}}$  setting is set to maximize resolution (0.2  $\mu$ m) but still allow coarse positioning (45  $\mu$ m/ second).

The TARGET/RETRACT allows the user to set a target location at a desired point. When it becomes necessary to back away from the experiment area, the user simply depresses the RETRACT button on the controller. The stage/actuator plugged into that axis (No.1), then automatically retracts to its full negative limit. The user can then return to the previously set position by simply depressing the TARGET button. The MC1000e-R1/4T uses a CE certified power supply as its source for clean DC power. All cables are shielded and a central ground lug is located on the junction box to ensure noise-free operation during sensitive electrophysiology experiments.

#### **Product Features**

- Multi-axis, single dial control
- Remote micrometer control

MC1000e-R1/4T

■ High and low speed settings

### Performance Specifications

 $\begin{array}{ll} \mbox{Minimum controllable motion} & 0.2 \ \mu \mbox{m} \\ \mbox{Maximum speed} & 1.5 \ \mbox{mm/sec} \\ \mbox{Power requirements} & 110-230 \ \mbox{VAC}, 50/60 \ \mbox{Hz} \\ \end{array}$ 

### **Related Products**

motorized micromanipulators	beginning	166
800 and 7000 series actuators		93
800 and $7000$ series translation stages		63
100cri stages		64
200cri stages		64
DR1000 digital readout		31

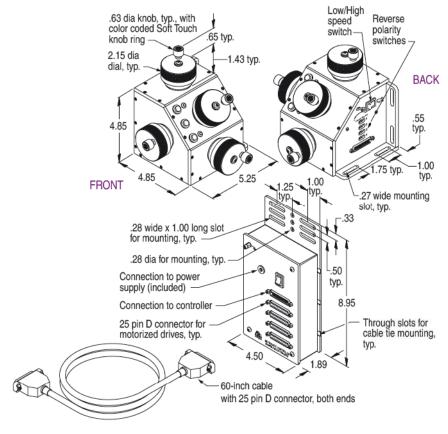
### **Order Information**

1–4-axis dial controller MC1000e-R1/4T junction box for MC1000e-R/T JB-MC1000e-R/T

# **Closed Loop Controllers**

**CE Certified** 

# 4 Axis Dial / MC1000e-R/T







MC1000e-R/T

# 4 Axis Micrometer Dial Control, with Target and Retract Feature

The MC1000e-R/T 4-axis dial controller acts as a remote micrometer control with a user selected target feature for 800 and 7000 series actuators, manipulators, and stages. The MC1000e-R/T uses encoder feedback from our closed loop devices to create an electronic link between the controller dial and the device being driven. This direct coupling to the encoder ensures smooth and coordinated motion between the controller and the drive. The encoder coupling enables the use of the DR1000 digital readout for repeated positioning requirements.

A two-position rocker switch is conveniently located on the side of the controller to allow for rapid and slow travel speed. The rapid % setting is set to maximize speed (1.5 mm/second) when the dial is turned at 240 RPM. The slow  $\varnothing$  setting is set to maximize resolution (0.2  $\mu$ m) but still allow coarse positioning (45  $\mu$ m/second).

The TARGET/RETRACT allows the user to set a target location at a desired point. When it becomes necessary to back away from the experiment area, the user simply depresses the RETRACT button on the controller. The stage/actuator plugged into that axis (No.1), then automatically retracts to its full negative limit. The user can then return to the previously set position by simply depressing the TARGET button. The MC1000e-R/T uses a CE certified power supply as its source for clean DC power. All cables are shielded and a central ground lug is located on the junction box to ensure noise-free operation during sensitive electrophysiology experiments.

#### **Product Features**

- 4-axis intuitive dial control
- Remote micrometer control
- High and low speed settings

# **Performance Specifications**

Minimum controllable motion	0.2 μm
Maximum speed	1.5 mm/sec
Power requirements	110-230 VAC, 50/60 Hz

# Related Products

MX7500 micromanipulator	170
MX7600 micromanipulator	169
831 stage	63
800 series actuators	93
100cri stage	64
200cri stage	64
DR1000 digital readout	31

### Order Information

4-axis dial controller	MC1000e-R/T

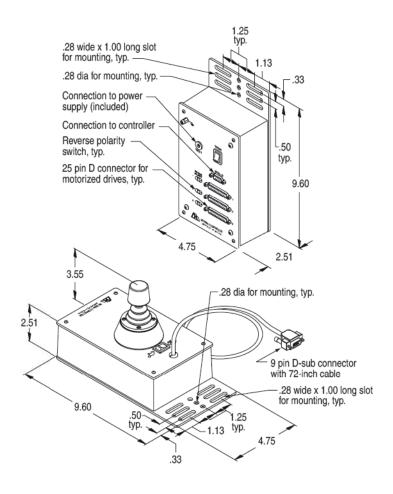




# **Closed Loop Controllers**

**CE Certified** 

# 3 Axis Joystick Control / MC1000e-J



# **Product Features**

- 3-axis, proportional speed control
- Ideal for XYZ motorized manipulator control
- High and low speed settings

#### Performance Specifications

Minimum controllable motion		1 µm
Power requirements	110-230 VAC,	50/60 Hz

MC1000e-J

### **Related Products**

MX7630 micromanipulator	168
MXMS-100cri series microscope translators	185
800 series actuators	93
831 stage	63
100cri stage	64
200cri stage	64
DR1000 digital readout	31

#### **Order Information**

3-axis joystick controller MC1000e-J

# 3 Axis Joystick Control

The MC1000e-J joystick controller is designed for micron-scale positioning of our 800 and 7000 series actuators, manipulators, and stages.

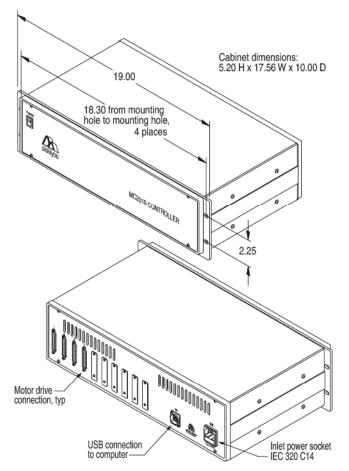
Polarity switches on the junction box allow the joystick motion to be set to match the direction of travel of the stage being driven. This feature ensures intuitive interaction between the joystick operator and the operation. The controller uses encoder feedback from the motor to drive the device. This encoder coupling enables the use of the DR1000 digital readout for repeated positioning requirements.

The MC1000e-J uses a CE certified power supply as its source for clean DC power. All cables are shielded and a central ground lug is located on the junction box to ensure noise-free operation during sensitive electrophysiology experiments.

# **Closed Loop Controllers**

# **CE** Certified









# **Computer Interface Control**

The MC2010 is a LabVIEW™ driven interface for our 800 and 7000 series actuators, manipulators, and stages. It is designed to be connected to the customer-supplied computer via the USB comport. The standard configuration is a 4 axis system and is capable of up to 10 axes of control.

The supplied LabVIEW™ executable has the ability to drive the stage/actuator with an external device. A traditional USB type PC game controller may be used to coarsely position the device, as well as define coordinate points to record and playback. The software's versatile parameter screens allows the user to custom fit AXIS HOME, ABSOLUTE POSITION, ZERO SET, VELOCITY, and INCREMENTAL AXIS JOG buttons. Interface commands are given in microns and are capable of 0.1 µm resolution when used with our motorized systems. The MC2010's industry standard 19-inch rack mounted cabinet comes with power supply and USB interface cords. The software is supplied on a CD.

# **Product Features**

- LabVIEW<sup>™</sup> Operating Software
- 4-axis, closed loop control
- USB I/O interface
- 19-inch Rack Mount Formfactor

#### Performance Specifications

Minimum controllable motion	0.1 μm
Maximum speed	1.7 mm/sec
Power requirements	110-230 VAC 50/60 Hz

# **Related Products**

MX7500 micromanipulator	170
MX7600 micromanipulator	169
831 stage	63
800 series actuators	93
100cri stage	64
200cri stage	64

### **Order Information**

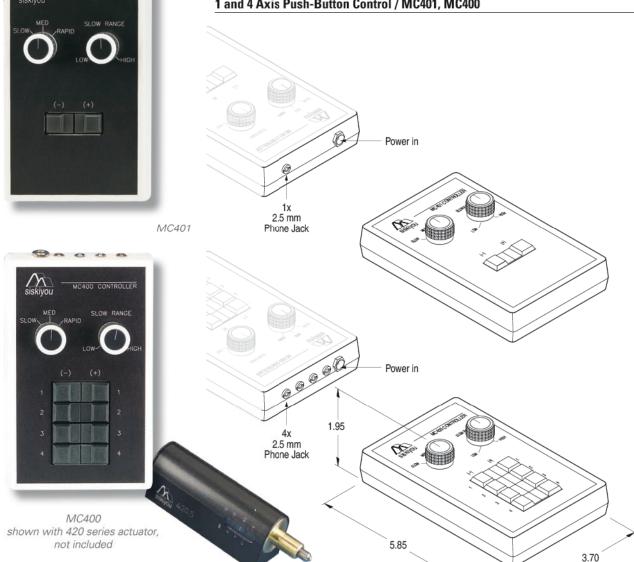
4-axis, compute	r interface	controller	MC2010
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# Open Loop Controllers

1 and 4 Axis Push-Button Control / MC401, MC400



### **Product Features**

- Economical DC controller
- Variable, high resolution speed control
- Preset rapid and medium speed settings

## Performance Specifications

with 400 series actuators under 8 pounds load Maximum speed:

800 µm/sec Rapid Medium 100 µm/sec 35 µm/sec Slow Range / High Slow Range / Low 5 µm/sec 110 VAC, 50/60 Hz Power requirements

### **Related Products**

400 series actuators

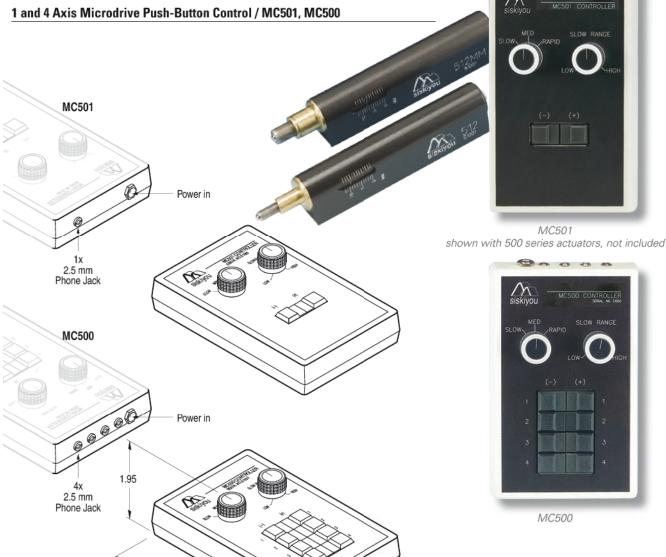
### **Order Information**

MC401 1-axis, open loop controller MC400 4-axis, open loop controller

# 1 and 4 Axis Push Button Control

The MC401 and MC400 open loop DC controllers are designed to drive our 400 series actuators. These controllers allow the user to operate from one to four of our 400 series actuators of any travel length. Both single and four-axis controllers have two preset speed settings: rapid (0.8 mm/second) and medium (100 µm/second). A third speed selection (slow) has a variable 330° potentiometer that enables settings from high speed (35 µm/second) to low speed (5 µm/second). With the speed selector set at the slowest settings, consistent 1.0 µm moves are easily made by the simple bump of an axis button. The MC400 and 401 controllers use wall mounted DC power supplies as their source. These noise-free DC controllers, along with our 400 series drives, can be used in proximity to electrophysiology experiments.







5.85

MC500 and MC501 open-loop DC controllers are specifically designed to drive series 500 and 500MM actuators. The 4-axis MC500 controller allows a user to operate as many as four series 500 actuators of any travel length. It has two preset speed settings: rapid (0.8 mm/ second) and medium (100  $\mu$ m/second). The third speed selector (slow) has a variable 330° potentiometer that enables settings from high speed (35  $\mu$ m/ second) to low speed (5  $\mu$ m/second). With the speed selector set at the slowest settings, consistent 1.0  $\mu$ m moves are easily made by the simple bump of an axis button. The MC500 controller uses a wall mounted DC power supply as its source. This noise-free DC controller, along with our 500 series drives, can be used in proximity to electrophysiology experiments.







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- Economical DC controller
- Variable, high resolution speed control
- Preset rapid and medium speed settings
- Variable, "slow" speed range

#### Performance Specifications

Maximum speed	
Rapid	300 µm/second
Medium	100 µm/second
Slow Range / High	30 µm/second
Slow Range / Low	10 µm/second
Power requirements	110 VAC, 50/60 Hz
Related Products	
500 series actuators	91

# Order Information

500MM series actuators

1-axis, open loop microdrive controller	MC501
4-axis, open loop microdrive controller	MC500

91

30



# **Motion Control**

# **Accessories and Hardware**

**CE Certified** 

# Switching and Junction Boxes / SB and JB Series



SB-MC1000e Series



- Control 2 to 4 micromanipulators with 1 controller
- Cost-effective and easy to assemble
- No position loss during switching
- Available in 9, 15 or 25 pin connector interface

# **Related Products**

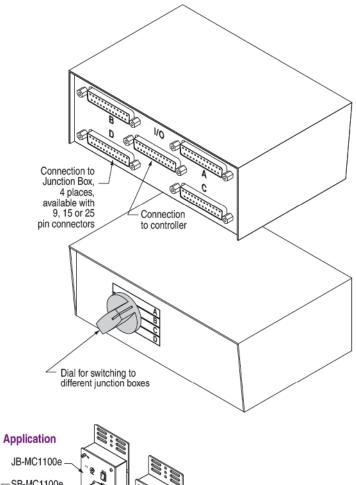
MC1000e-J motion controller	26
MC1000e motion controller	22
MC1100e motion controller	22
MC1000e-R/T motion controller	25
DR1000 digital readout	31

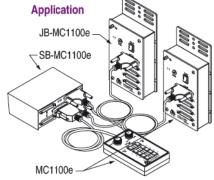
# **Order Information**

# **Switch Boxes**

for MC1000e	SB-MC1000e
for MC1100e	SB-MC1100e
for MC1000e-R/T	SB-MC1100e
for MC1000e-R1/4T	SB-MC1100e
for MC1000e-J	SB-MC1000e-J

iction Boxes	
for MC1000e	JB-MC1000e
for MC1000e-R/T	JB-MC1000e-R/T
for MC1000e-R1/4T	JB-MC1000e-R/1
for MC1100e	JB-MC1100e
for MC1000e-J	JB-MC1000e-c



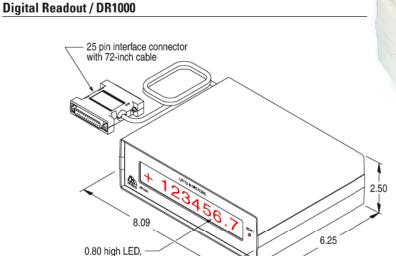


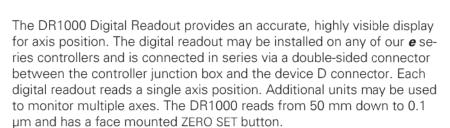
# **Switching and Junction Boxes**

Our switching box allows control of one to four 4-axis micromanipulators by one controller (MC2010 excluded). The basis of the design is simple and requires only an extra controller junction box for each added micromanipulator or motor drive group (up to four per group). Junction boxes must be purchased separately, however this is more cost-effective than individual handheld control units. When used with the MC1100e controller, the user can save a "target" location for each manipulator independent of the operation of the others even after switching between micromanipulators. The DR1000 is also compatible with this switching box and will allow the user to reposition without the use of an expensive computer based controller. The switch box comes with enough cables to attach four junction boxes, and all connections are shielded.

# **Accessories and Hardware**

units in microns





The DR1000 receives clean DC power through the junction box of the MC1000e series controller. All cables are shielded to ensure noise-free operation during sensitive electrophysiology experiments. The slim and light weight case may be mounted separately or stacked on top of each other in multiple axis applications



DR1000

#### **Product Features**

- Economical position readout solution
- Large, easy to read, digital display
- Compatible with all e series controllers

### Performance Specifications

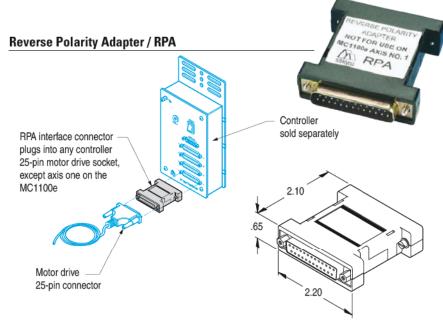
Minimum travel increment	0.1 μm
Maximum travel display	500,000 μm
Accuracy	99

#### **Related Products**

MC1000e-1 motion controller	22
MC1000e-R1/4T motion controller	24
MC1000e-J motion controller	26
MC1000e motion controller	22
MC1100e motion controller	22
MC1000e-R/T motion controller	25

### **Order Information**

single-axis digital readout DR10
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The RPA is an interface plug that reverses the motion direction of stages and actuators. Used to reverse axis direction relative to controller. Use on MC1000e-1, MC1000e, and MC1100e (except axis number 1).

#### **Product Features**

- Economical solution to reversing polarity
- Intuitive controller adapter
- Maintains gender orientation

#### Performance Specifications

Pinout pattern	standard 25-pin
	"D" connector
	Male to Female
Power requirements	12 volt DC maximum

### **Related Products**

MC1000e-1 motion controller	22
MC1000e motion controller	22
MC1100e motion controller	22

#### Order Information

reverse	polarity adapter	RPA